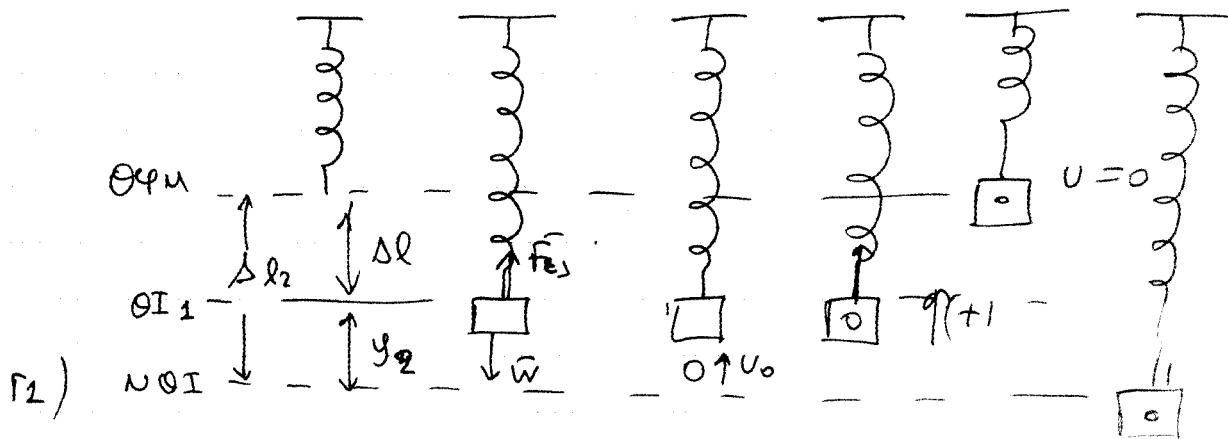


ΘΕΜΑ Γ

$$m_1 = 1 \text{ kg}$$

$$\Delta l = 0,05 \text{ m}$$

$$m_2 = 1 \text{ kg}$$



$$\Theta\Gamma(1) \quad \Sigma F_y = 0 \Rightarrow W = F_{es} \Rightarrow m_1 g = k \Delta l$$

$$k = \frac{10}{0,05} \Rightarrow k = 200 \text{ N/m} \quad \checkmark$$

(ΝΘΙ)

$$\Sigma F_y = 0 \Rightarrow W_{\Sigma} = F_{es}' \Rightarrow (m_1 + m_2)g = k \Delta l_2$$

$$20 = 200 \Delta l_2 \Rightarrow \Delta l_2 = 0,1 \text{ m} \quad \checkmark$$

ΑΔΕΤ οταν το ελατήριο έχει το Φ.Μ

$$E_1 = K + U_1$$

$$\frac{1}{2} k A^2 = 0 + \frac{1}{2} k \Delta l_2^2$$

$$A = \Delta l_2 = 0,1 \text{ m}$$

$$U_0 = m$$

U_ε & U_ε

12) ΑΔΕΤ απέναντι μετωπικά των κρούσεων

$$E_T = K + U_T =$$

$$\frac{1}{2} D A^2 = \frac{1}{2} (m_1 + m_2) U_\varepsilon^2 + \frac{1}{2} D (\Delta l_2 - \Delta l)^2$$

$$200 \cdot 0,02 = 2 \cdot U_\varepsilon^2 + 200 \cdot 0,02^2$$

$$2 = 2 U_\varepsilon^2 + \frac{1}{2} \Rightarrow \frac{3}{2} = 2 U_\varepsilon^2 \Rightarrow U_\varepsilon = \frac{\sqrt{3}}{2} \frac{m}{s}$$

ΑΔΟ

$$\vec{P}_{\text{πρ}} = \vec{P}_{\text{μετ}} \Rightarrow m_2 U_0 = (m_1 + m_2) U_\varepsilon$$

$$1 \cdot U_0 = 2 \cdot \frac{\sqrt{3}}{2} \Rightarrow U_0 = \sqrt{3} \frac{m}{s}$$

$$K_{\text{πρ}} = \frac{1}{2} m_2 U_0^2 = \frac{3}{2} J$$

$$13) |\Delta P_2| = |m_2 U_\varepsilon - m_2 U_0| = \left| \frac{\sqrt{3}}{2} - \sqrt{3} \right| =$$

$$|\Delta P_2| = \left| -\frac{\sqrt{3}}{2} \frac{m}{s} \right| = \frac{\sqrt{3}}{2} \frac{m}{s}$$

με φορά αντίθετη προς $\vec{U}_0$

14) $t=0$

$$y = +(\Delta l_2 - \Delta l) = +y_g \Rightarrow y = 10,05 \text{ m}$$

$$U > 0$$

$$y = A \sin(\omega t + \varphi_0) \Rightarrow y = y_2$$

$$y_2 = A \sin \varphi_0 \Rightarrow 0,05 = 0,2 \sin \varphi_0$$

$$\sin \varphi_0 = \sin \frac{\pi}{6} \Rightarrow \varphi_0 = \begin{cases} 2k\pi + \frac{\pi}{6} \\ 2k\pi + \frac{5\pi}{6} \end{cases} \quad \begin{matrix} \text{for } \varphi_0 \in [0, 2\pi) \\ \Rightarrow \end{matrix}$$

$$\varphi_0 = \begin{cases} \frac{\pi}{6} \text{ rad} \\ \frac{5\pi}{6} \text{ rad} \end{cases}$$

$$U > 0 \Rightarrow \sin \varphi_0 > 0 \Rightarrow \varphi_0 = \frac{\pi}{6} \text{ rad}$$

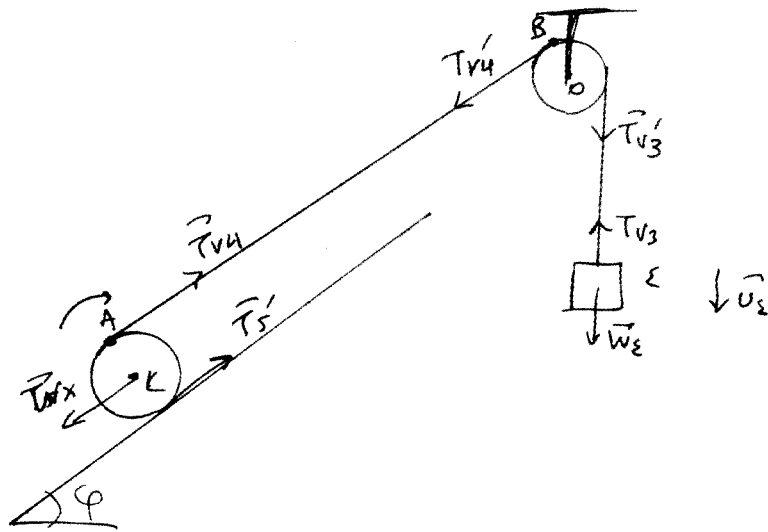
ΟΕΦΕ

$$D = k \Rightarrow (m_1 + m_2) \omega^2 = k$$

$$2 \omega^2 = 200 \Rightarrow \omega = 10 \frac{\text{rad}}{\text{s}}$$

$$y = 0,2 \sin\left(10t + \frac{\pi}{6}\right) (\text{m})$$

Δ2)



Επειδή το μήκος δε γλιστρά.

$$v_A = v_B = v_ε \Rightarrow 2v_{cm} = \omega_T R_T = v_ε \Rightarrow$$

$$2a_{cm} = R_T \cdot \alpha_T = \alpha_I \quad (5)$$

σώμα (ε)Θ Ν Μ Κ

$$\sum F_y = m a_I \Rightarrow W_ε - T_{v3} = m a_I \Rightarrow$$

$$T_{v3} = 20 - 2a_I \quad (6)$$

προκαταία (Θ Ν Ε Κ)

$$\sum \tau_{O_I} = I \alpha_T \Rightarrow T_{v3}' R_T - T_{v4}' R_T = \frac{1}{2} M_T R_T \frac{a_I}{R_T} \quad (5)$$

$$\Rightarrow 20 - 2a_I - T_{v4} = a_I \Rightarrow T_{v4} = 20 - 3a_I \quad (7)$$

κεΑΙ σφραΘ Ν Μ Κ

$$\sum F_x = M_K a_{cm} \Rightarrow T_{v4} + T_{v5}' - W_x = M_K \frac{a_I}{2} \quad (7)$$

$$20 - 3a_I + T_{v5}' - 10 = a_I \Rightarrow$$

$$T_{v5}' = 4a_I - 10 \quad (8)$$

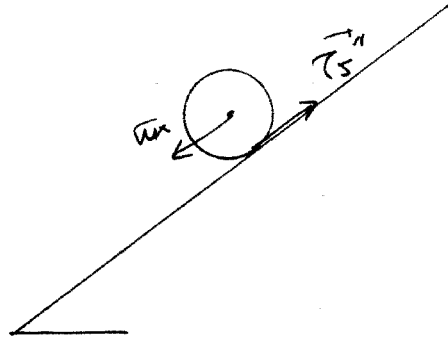
Θ Ν Ε Κ

$$\sum \tau = I_{cmK} \alpha_K \Rightarrow T_{v4} R_K - T_{v5}' R_K = \frac{1}{2} M_K R_K^2 \frac{a_{cm}}{R_K} \quad (7)$$

$$\Rightarrow 20 - 3a_I - 4a_I + 10 = \frac{a_I}{2} \Rightarrow$$

$$30 = 7.5 a_I \Rightarrow a_I = 4 \frac{m}{s^2} \quad \mu_K a_{cm} = 2 \frac{m}{s^2}$$

Δ3)



$$\alpha_{cm} = \frac{a}{2} = 2 \text{ m/s}^2$$

$$v_{cm} = \alpha_{cm} t_1 = v_0 \Rightarrow v_0 = 1 \text{ m/s}$$

ΘΝΜΚ

$$\Sigma F_x = M \alpha_{cm}' \Rightarrow T_s'' - w_x = M \alpha_{cm}' \Rightarrow$$

$$\boxed{T_s'' = 10 + 2 \alpha_{cm}'} \quad (9)$$

ΘΝΕΚ

$$\Sigma \tau = I_{cm} \alpha_{cm}' \Rightarrow -T_s'' R_k = \frac{1}{2} M_k R_k^2 \frac{\alpha_{cm}'}{R_k} \quad (9)$$

$$-10 - 2 \alpha_{cm}' = \alpha_{cm}' \Rightarrow$$

$$\alpha_{cm}' = -\frac{10}{3} \frac{\text{m}}{\text{s}^2}$$

ο κώλυος θα σταματήσει όταν $v_{cm} = 0$

$$v_{cm} = v_0 - |\alpha_{cm}'| \Delta t \Rightarrow$$

$$0 = 1 - \frac{10}{3} \Delta t \Rightarrow \Delta t = 0,3 \text{ sec}$$

$$\underline{\underline{t_2 = t_1 + \Delta t = 0,8 \text{ sec}}}$$

$$\Delta 4) \quad S_{cm_2} = \frac{1}{2} a_{cm} t_1^2 = \frac{1}{4} m = 0,25 m$$

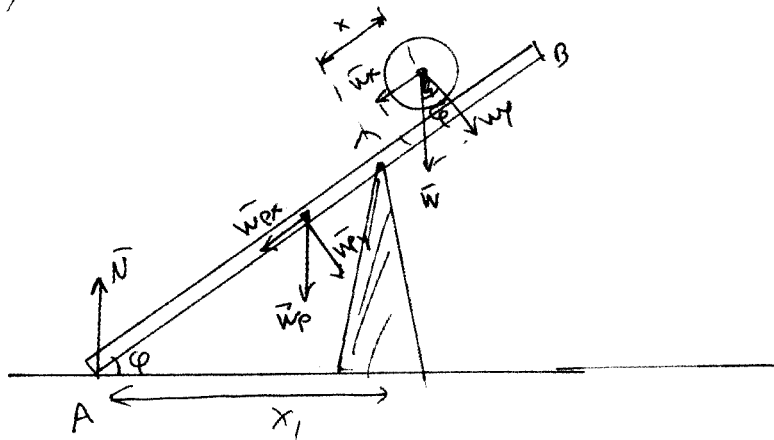
$$S_{cm_2} = v_0 \Delta t - \frac{1}{2} |a_{cm}| \Delta t^2$$

$$S_{cm_2} = 0,3 - \frac{1}{2} \cdot \frac{10}{3} \cdot \frac{9}{100}$$

$$S_{cm_2} = 0,15 m$$

$$S_{02} = S_{cm_1} + S_{cm_2} = 0,4 m$$

$\Delta 5)$



$$\sum \tau(r) = 0 \Rightarrow$$

$$- w_g \cdot x + w_{py} \cdot (r_A) - N \cdot x_1 = 0$$

$$N \cdot (A r) \overset{\text{sup}}{\cancel{\sin \phi}} = \cancel{M g \sin \phi} \cdot (r_A) - \cancel{M g \sin \phi} \cdot x \Rightarrow$$

$$N \cdot \frac{5}{2} = 2 \cdot 10 \cdot 0,2 - 2 \cdot 10 \cdot x$$

$$N \cdot \frac{5}{2} = 4 - 20x \Rightarrow$$

$$5N = 8 - 40x \Rightarrow \boxed{N = \frac{8 - 40x}{5} \text{ (N)}} \quad (10)$$

* ράβδος μπορεί να ανατραπεί όταν κλιθεί
πέρασε το (r).

$$S_{02} = 0,4 \text{ m}$$

$$x_{\max} = S_{02} - r\Delta \Rightarrow x_{\max} = 0,4 - 0,2 = 0,2 \text{ m}$$

$$\textcircled{10} \Rightarrow N = \frac{8-8}{5} = 0$$

Μοτίς που δεν ανατρέχει